

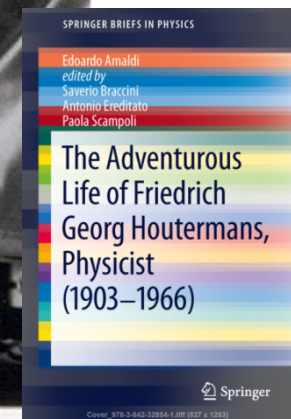
ATMic: Fast 4π tracking based on GPUs and its framework

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Scanners in Bern some time ago



F.G. Houtermans im Kreise seiner Scannerinnen im
Physikalischen Institut Bern 1955/56



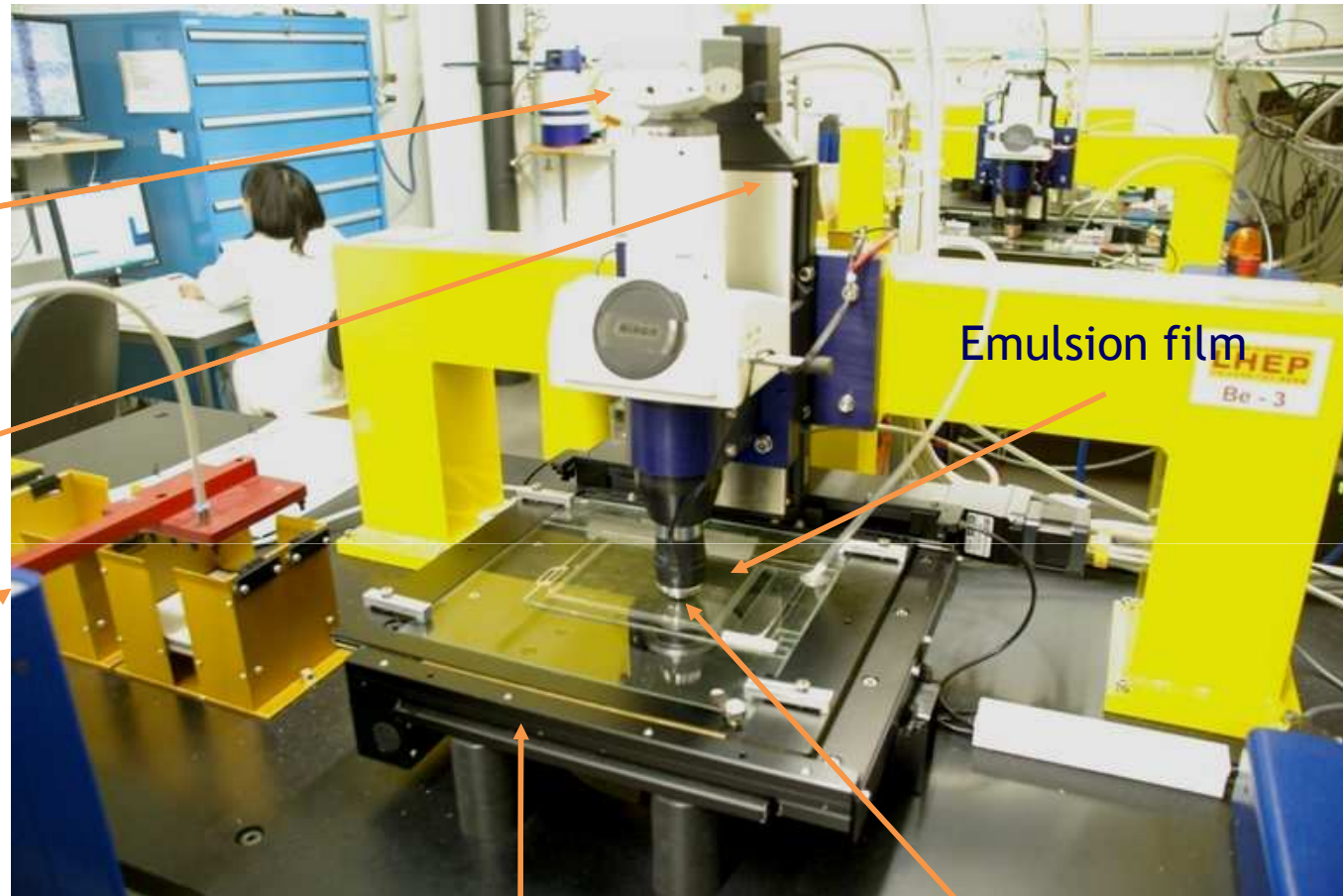
Conventional system : OPERA Microscope

CMOS camera
1280×1024 pixel
256 gray levels
376 frames/sec
(Mikrotron MC1310)

Z stage (Micos)
0.05 μm nominal
precision

Automatic Plate Changer

20 min / cm^2



Emulsion film

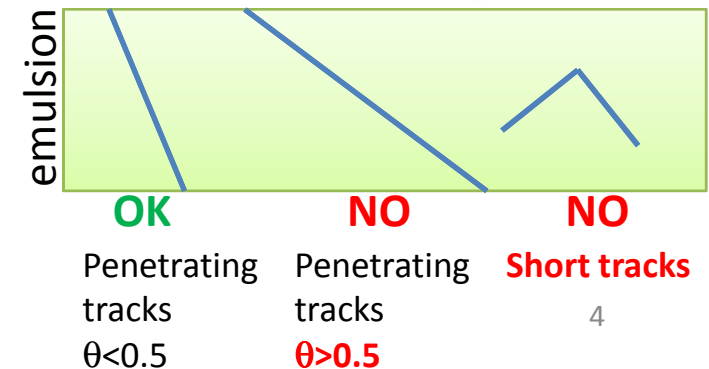
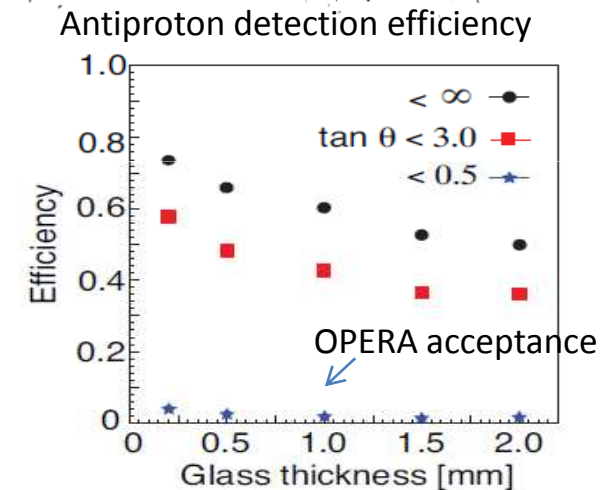
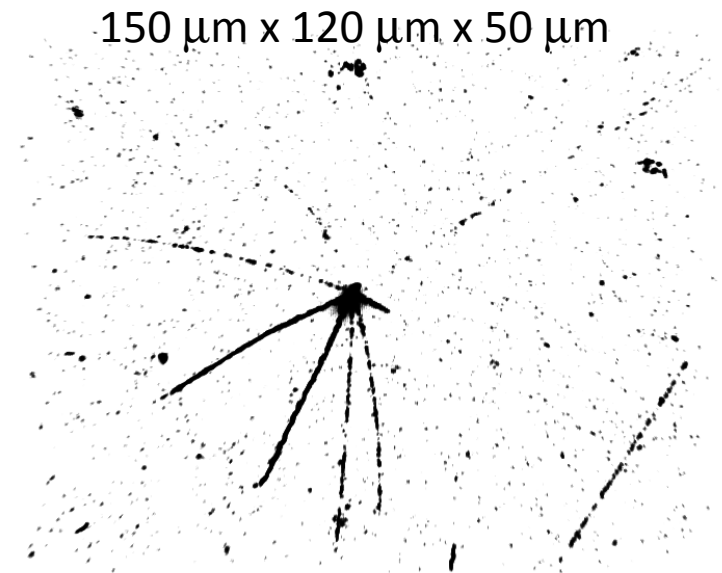
XY stage (Micos)
0.1 μm nominal
precision

objective (Dry 50× NA 0.95)

Limitation of conventional system

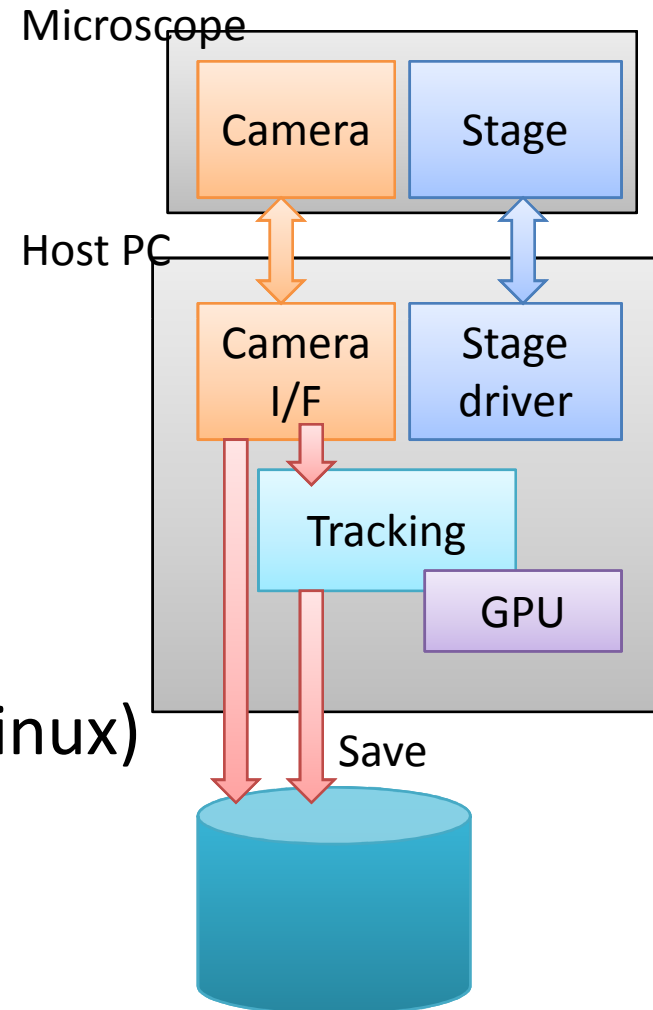
- **Small angular acceptance**
 - $\theta < 0.5$
 - For AEGIS, we need 4π tracking!
- **Tracking tuned for penetrating particles**
 - Limited information can be extracted
 - Scattered track cannot be followed
 - Short tracks which start and stop in emulsion cannot be detected
- **Less flexibility**
 - Development beyond OPERA is difficult

→ **New Framework : ATMic**



ATMic

- A framework for general purpose scanning
 - Data classes
 - Stage driver
 - Camera interface
 - Tracking
 - Reconstruction
 - Display (Virtual microscope)
 - GPU interface
- ROOT-base program
- OS independent (Windows or Linux)



ATMic classes

- All classes are ROOT classes
- Well documented
 - Transparent for users
- Capable to accommodate several tracking algorithms

ROOT

```
//create the file, the tree and a  
TFile f("tree.root","create");  
TTree t("t1","a simple tree with  
t1.Branch("px","spn","p/F");  
t1.Branch("py","spj","p/F");
```

Quick Links: | ROOT Homepage | Class Index | Class Hierarchy

ATMic

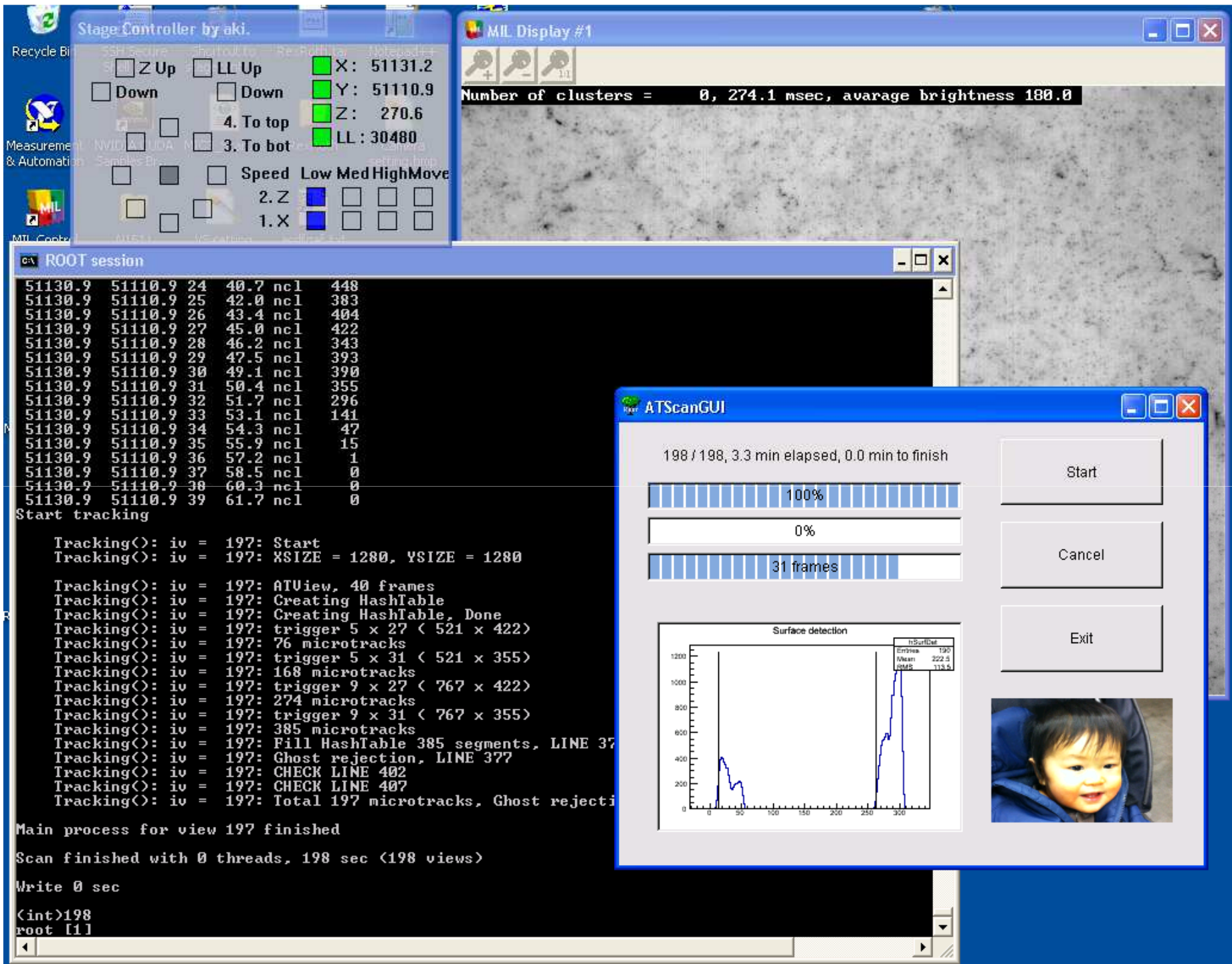
Class Index

Modules

Jump to

A ATB ATBasetrackV ATC ATClu ATClusters ATCu ATF ATH A
ATImageDisplayH ATImageDisplayO ATIn ATL ATLine3DC ATM AT
ATSegm ATSegmentC ATT ATTracki ATTrackingC ATTrackingCluster2
ATVer ATVi ATViewH ATViewP ATViews G

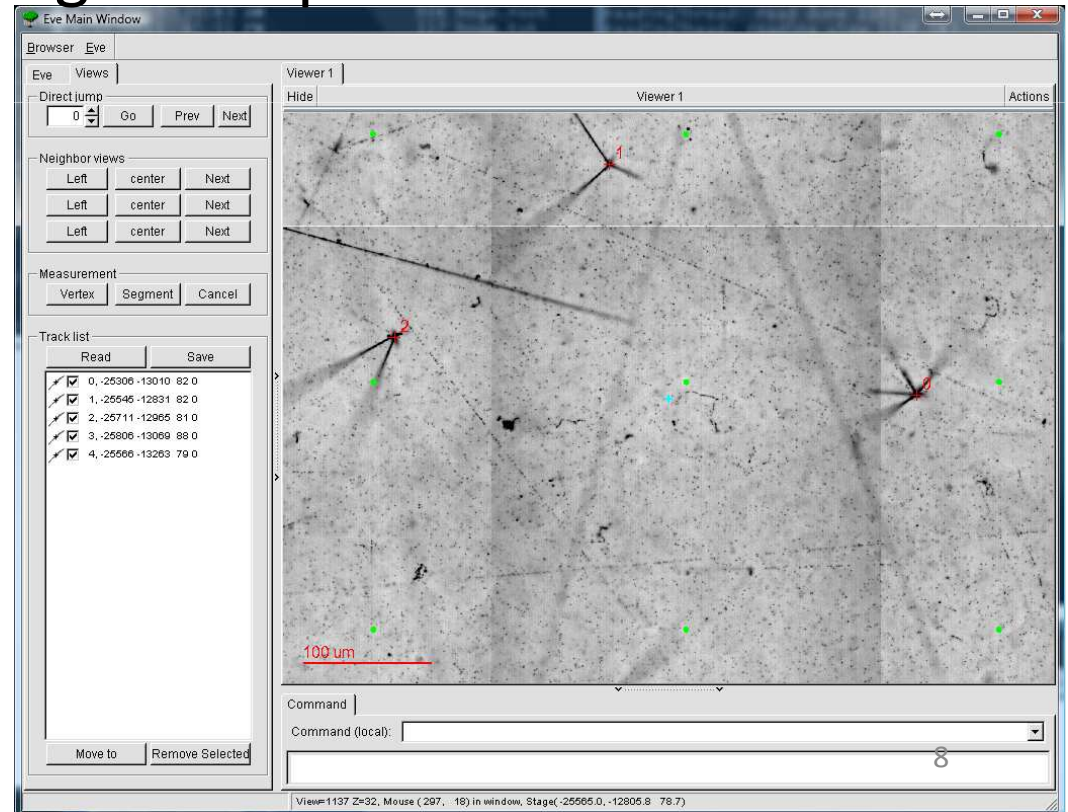
ATAffine2D	2D affine parameters
ATBasetrack	basic Segment class
ATBasetrackV	basic Segment class
ATClonesArray	Container of TObject
ATCluster	Cluster class
ATClustersArray	Base class of data
ATCuda	
ATFrame	8 bit image
ATHashTable	ATHashTable
ATHashTable2	ATHashTable2
ATImageDisplay	
ATImageDisplayHandler	
ATImageDisplayOverlay	a class for draw overlays, i.e. scale bars.
ATIntegerDialog	Input GUI for integer number.
ATLine3D	3D line
ATLine3DC	3D line
ATMic	
ATNoTracking	Tracking for G1
ATObject	Base class of data
ATPred	prediction
ATSegV	basic Segment class
ATSegVC	basic Segment class
ATSegment	basic Segment class
ATSegmentC	Segment with clusters
ATTrackV	Track class for ATSegV
ATTracking	Tracking abstract
ATTrackingCluster	Tracking with clusters
ATTrackingCluster2	Tracking with clusters
ATTrackingG1	Tracking for G1
ATVMDataManager	Virtual Microscope data manager
ATVector3	3D Vector class like TVector3 (specially made for CUDA



Virtual microscope

- ROOT & OpenGL base programming
- Dynamic data management
 - Necessary to deal Tera-byte scale data
 - Multithreads for display / reading data
- Nice also for students and general public

See image display

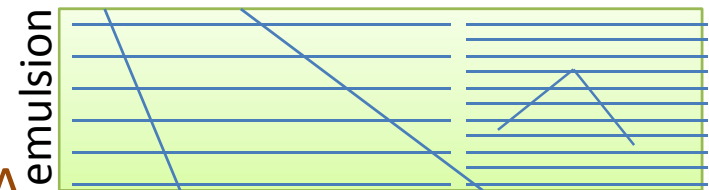


Fast 4 π tracking

- General purpose tracking
 - 8 times larger angular acceptance in solid angle than OPERA

	AEGIS	OPERA
acceptance in θ (rad)	π	0.5
Acceptance in steradian	12.6 (4π)	1.5

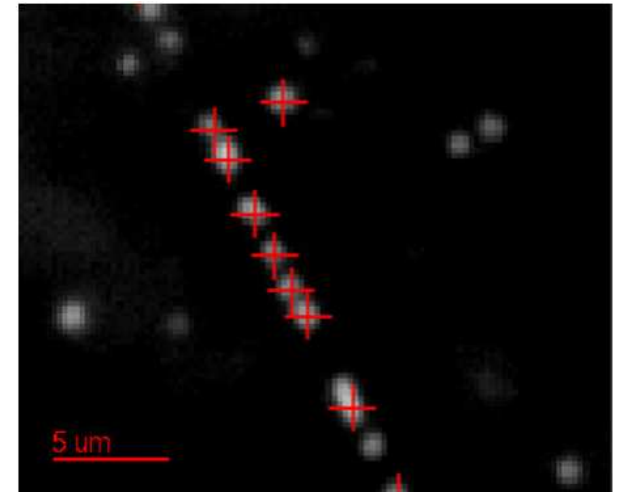
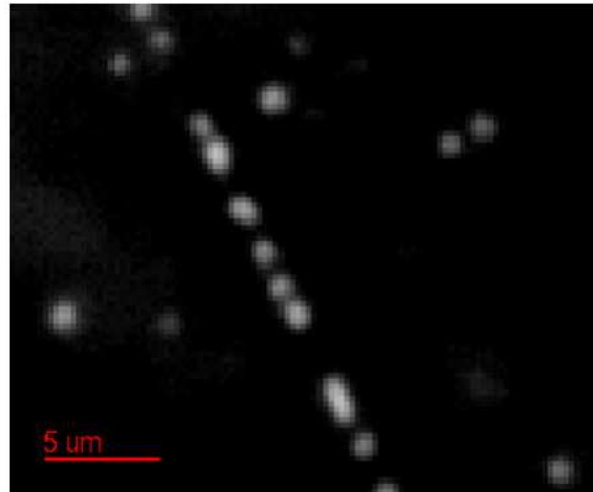
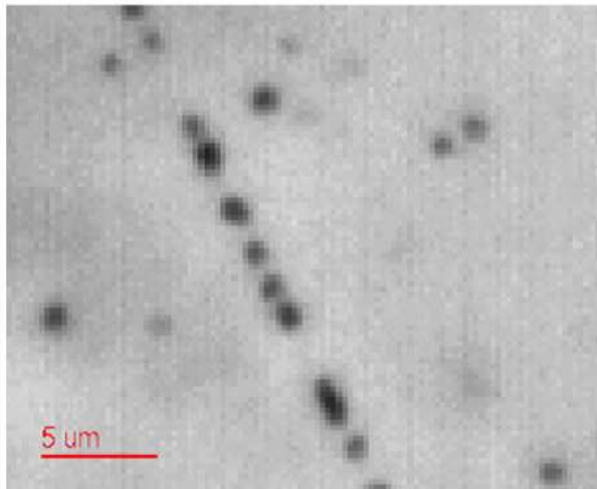
- Detection of short tracks
 - finer sampling (16-**>40** frames/view)
 - ~~quick algorithm~~
 - start and stop points information
 - **>10 times more computing than OPERA**



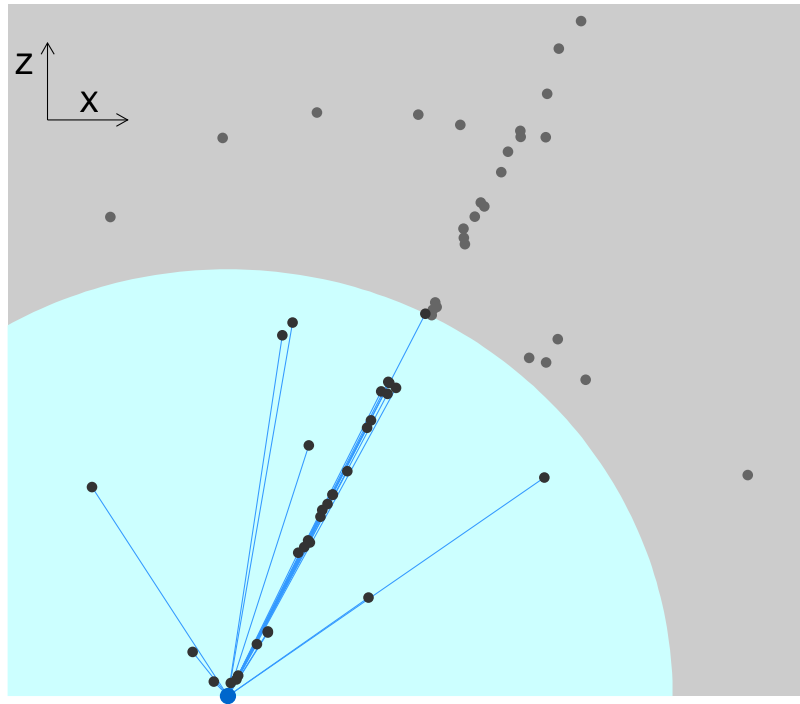
- **→ 2 order of magnitude larger computation is needed when it is compared OPERA algorithm**

3D Filtering

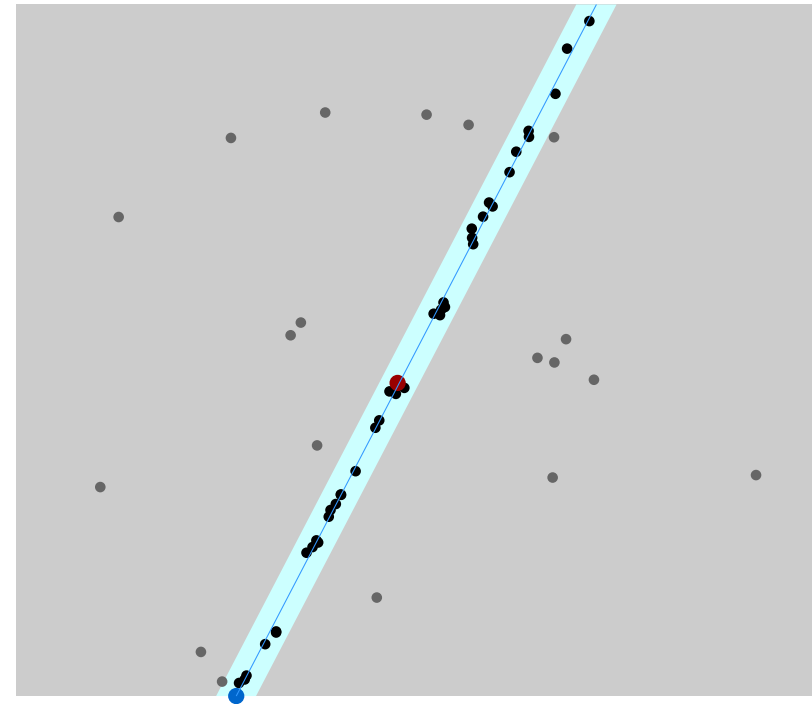
- Pixel by pixel gain control
- BG subtraction
- 3D grain recognition



Tracking algorithm

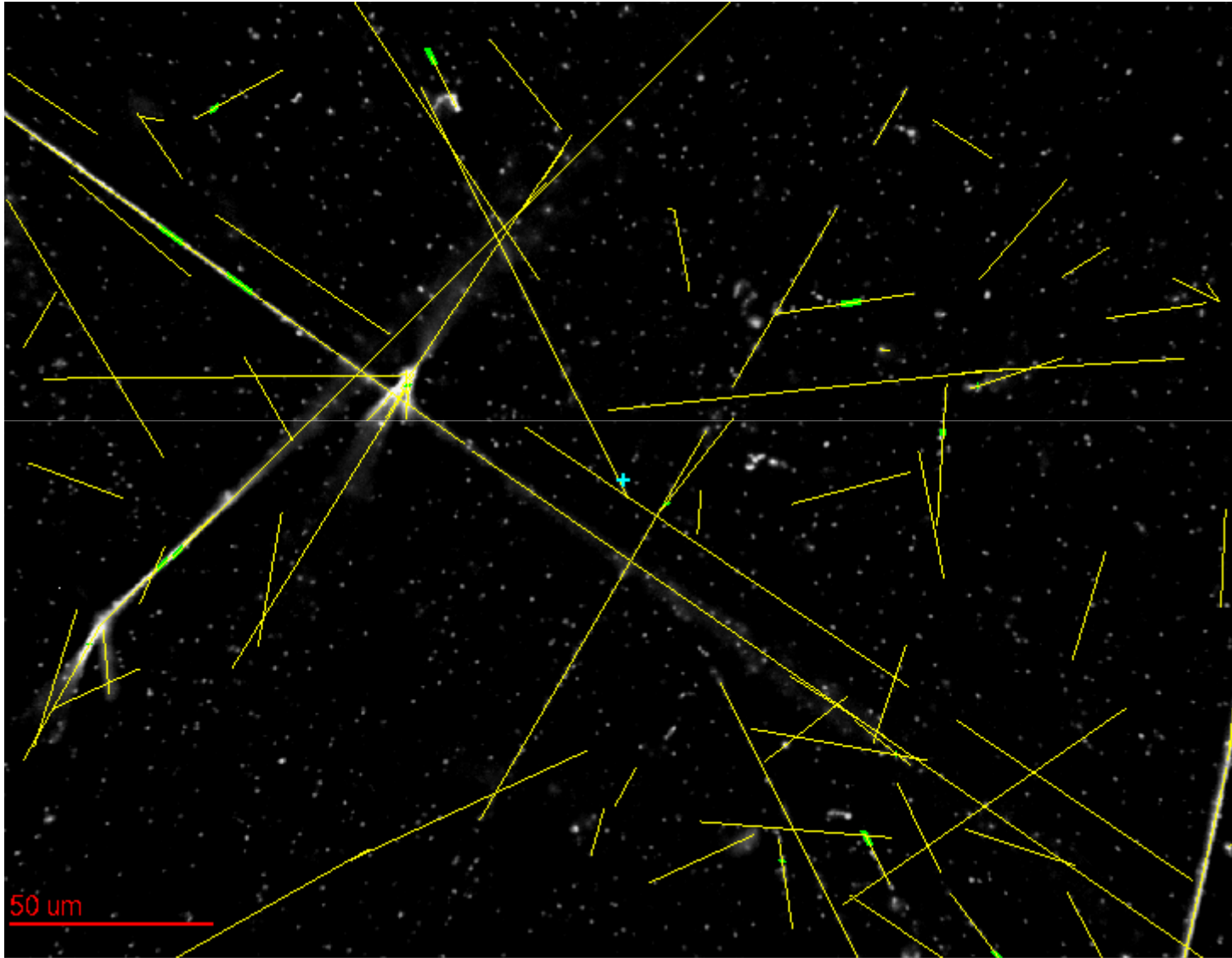


- Find any 2 grains combination within a certain distance, forming seeds (lines).



- Count number of clusters along the lines. if number of clusters is bigger than a threshold, classify as a track.

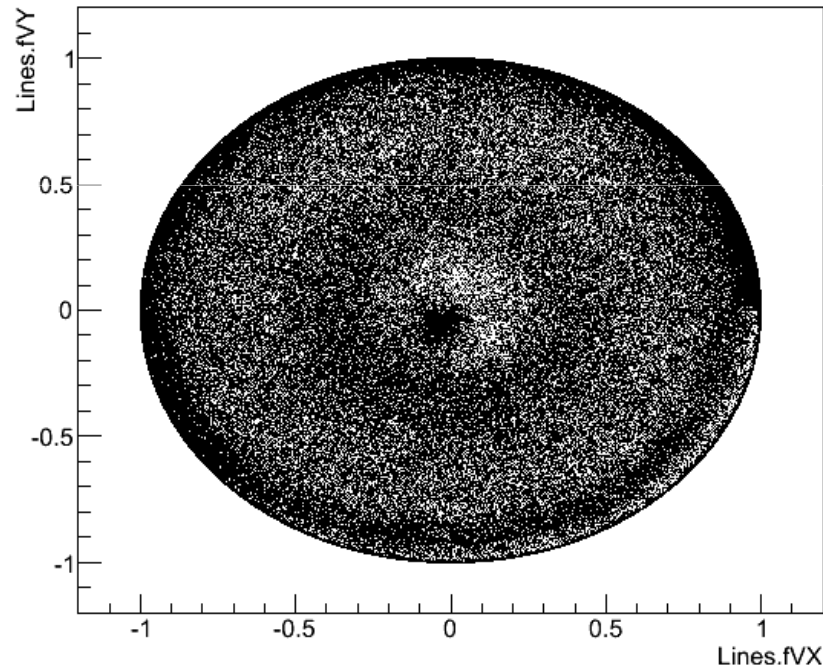
Example of a view (SEE DISPLAY)



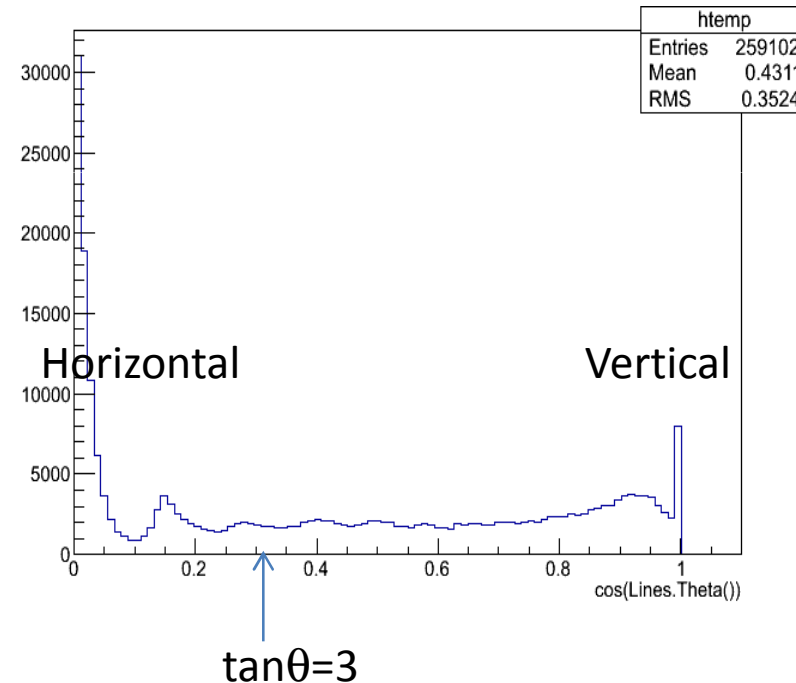
all tracks recognized by Aki are reconstructed as well by the algo.

Reconstructed angular distributions AEgIS film exposed to antiprotons

Angle as 3D unit vector
VX-VY



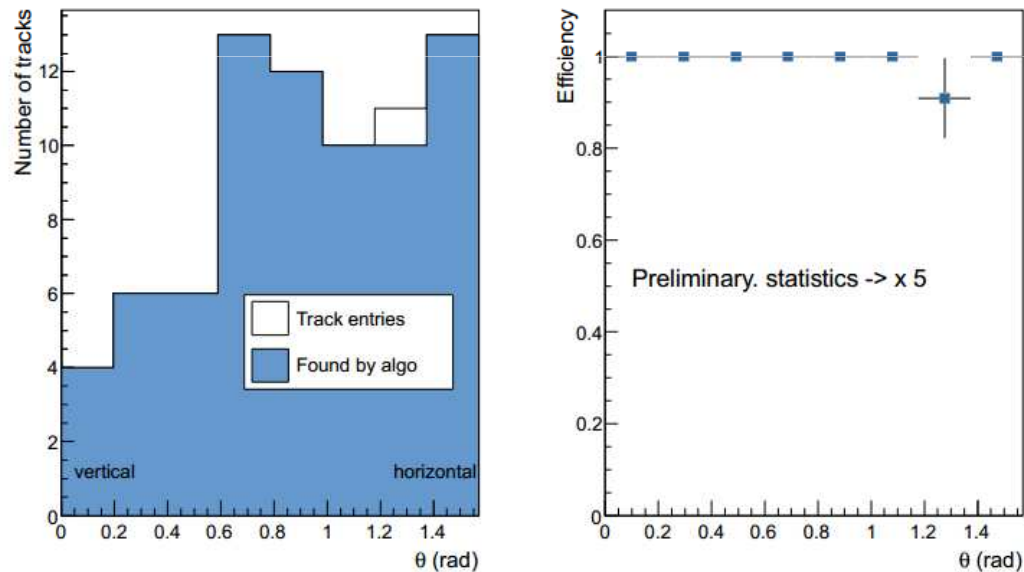
Cosθ distribution
θ : azimuthal angle



The tracking covers 4π solid angle

Efficiency of tracking

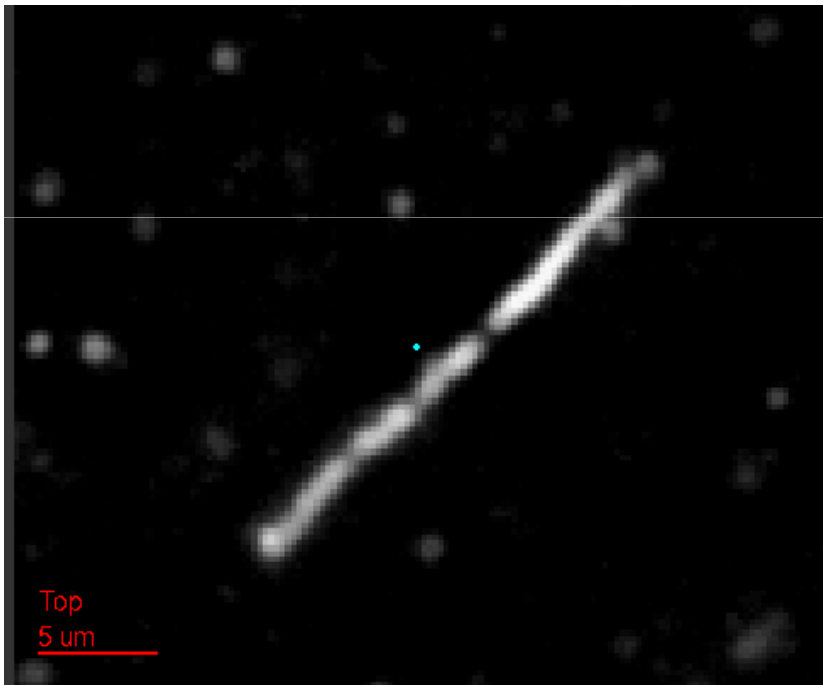
- Efficiency has been checked by comparing unbiased manual measurement
 - Tracks longer than 10 microns.
 - Half of tracks are heavily ionizing particles



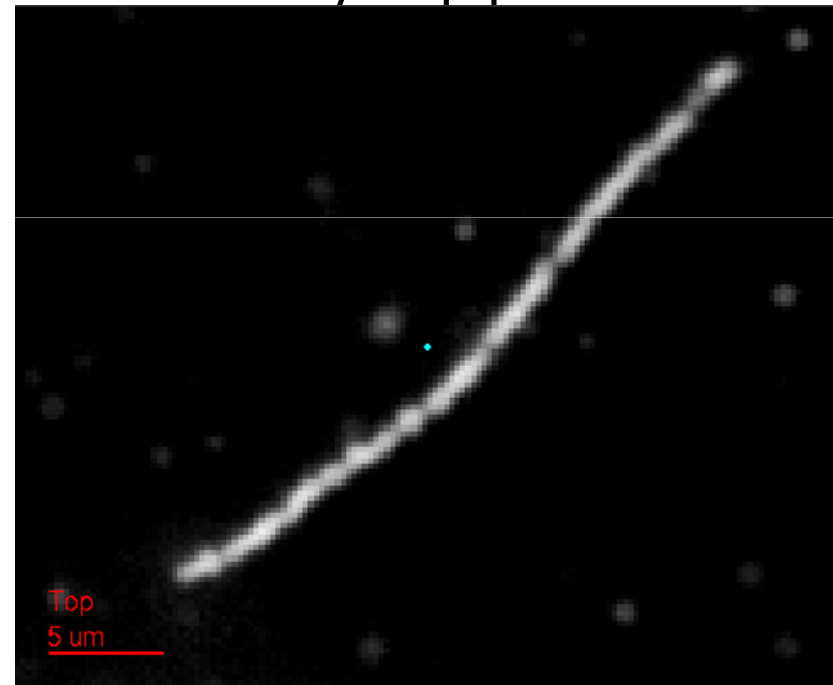
- High tracking efficiency is achieved.

Example of proton tracks recoiled by neutrons

- Proton tracks by 2.5 MeV neutrons.
- (horizontal tracks are chosen for demo)
- Short tracks are reconstructed with start/stop point



A 30 micron short track is reconstructed



A scattered track is reconstructed as 2 segments

Reconstruction of emulsion data

- Goal of processing time = **0.2 sec/view** ($\rightarrow \sim 10 \text{ cm}^2/\text{microscope}$)
 - Typical data unit “view” = 1280 x 1024 pixels x 40 frames = 52 Mbyte
 - FOV = 300x250 microns
 - image filtering, 3D grain recognition, 3D track reconstruction
- With single thread programming
 - ~**10 sec/view** with high spec CPU.
- need factor **50 times faster processing**
- \rightarrow **Track reconstruction based on GPU technology**
 - GPU = Graphic Processing Unit
 - Advantage : Parallel processing with thousands of processing unit



Use of GPU, as far as I concerned

- In 2003, use of GPU shaders for tracking
 - Use of alpha blending for tracking
 - Not enough speed... gave up
- In 2006, CUDA library has been released by NVIDIA
 - General purpose library
- In 2008, restarting to use GPUs
 - Suggestion to use GPU to the OPERA collaboration → a few successful implementation. See T. Fukuda, V. Tioukov
- After several interruptions, achieved a reasonable result recently

Processing machine equipped with 3 GPUs

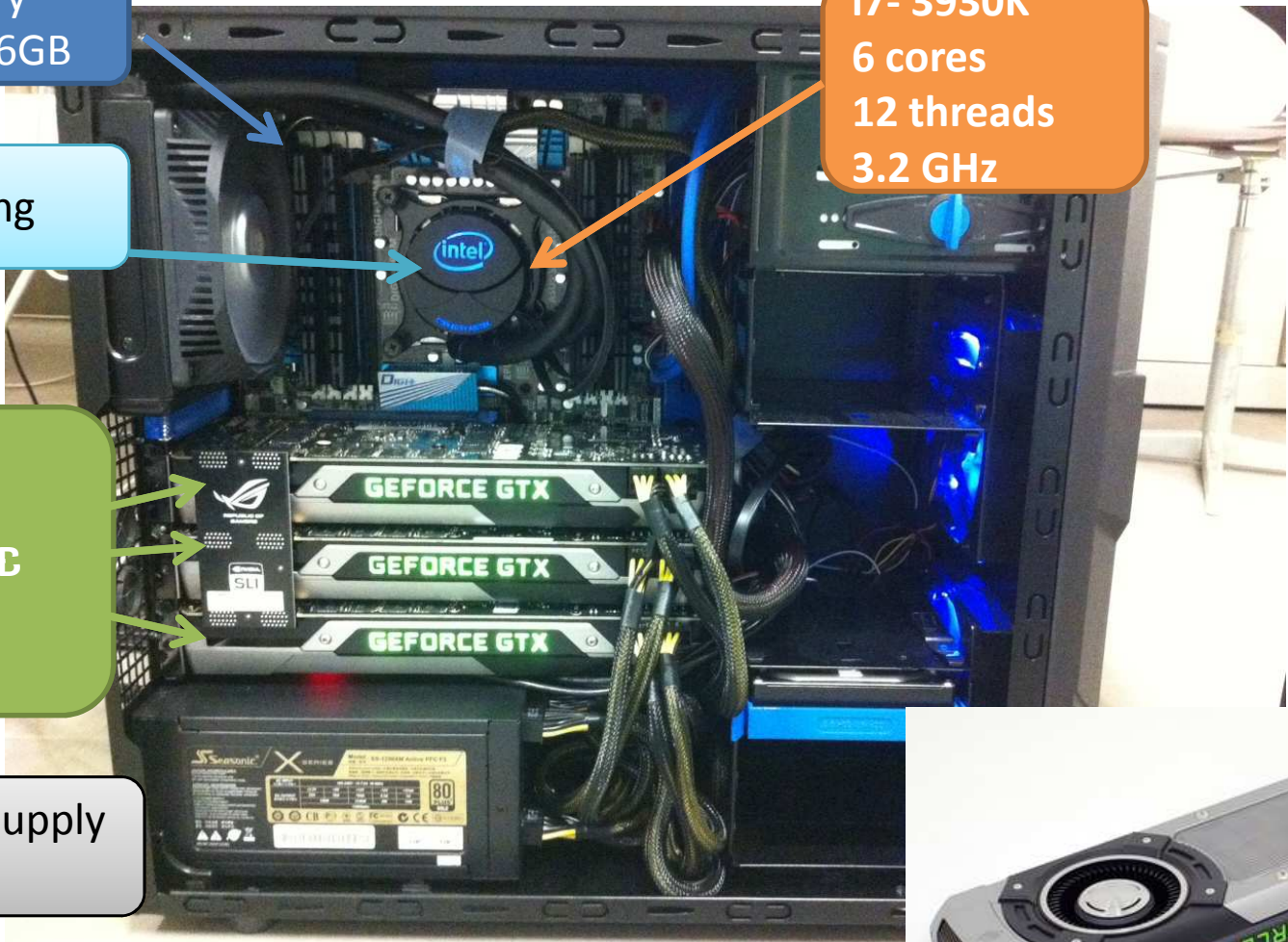
Fast memory
DDR3 2400, 16GB

Water cooling

Geforce GTX
TITAN x 3
2688 cores, 6GB
memory, 4.5
TFLOPs in each

Strong power supply
1250 W

i7- 3930K
6 cores
12 threads
3.2 GHz

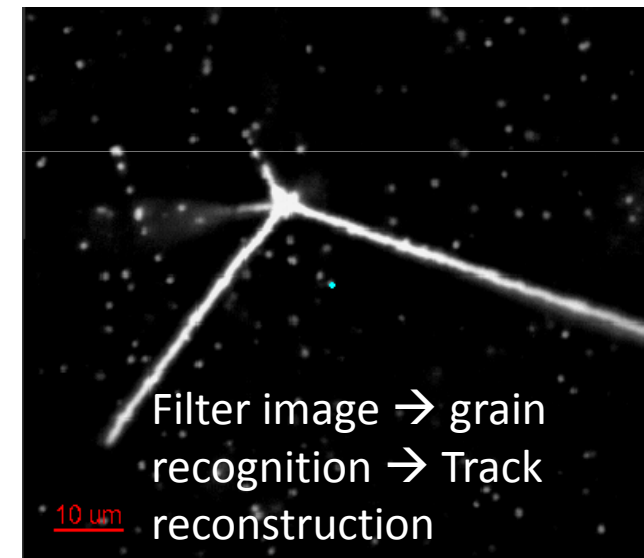


Processing time by single thread

- Goal: 0.2 sec/view
- Same algorithm was implemented on CPU and GPU program.

	1 CPU (sec/view)	using 1 GPU (sec/view)	Gain
Image filtering	0.55	0.022	x25
3D grain reco	0.20	0.025	x8
3D tracking	5.90	0.373	x16

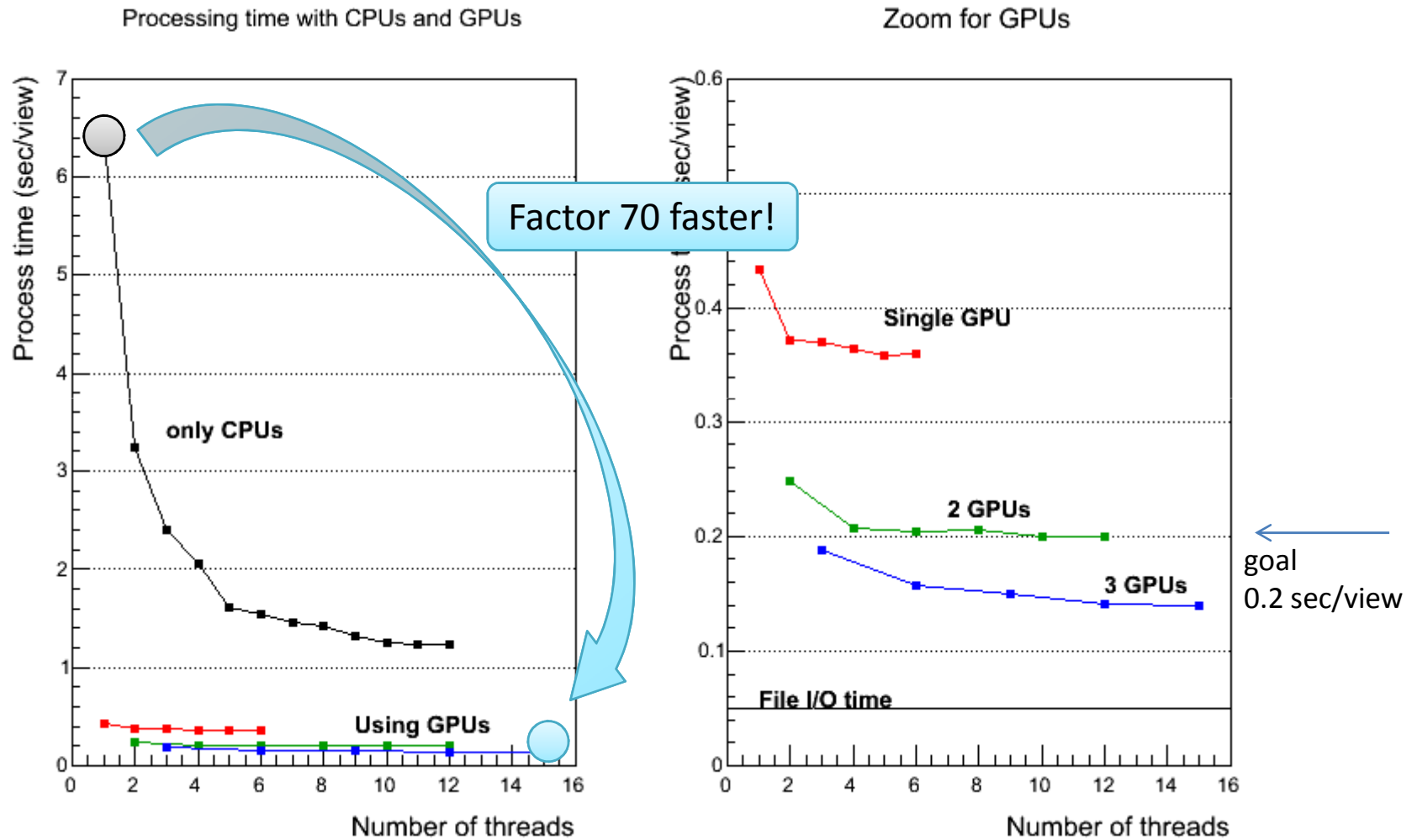
i7- 3930K 6 cores, 12 threads, 3.2 GHz
Geforce GTX TITAN, 2688 cuda cores



Single-CPU-thread and single-GPU is not enough to achieve the goal.

→ **Multi-CPU-thread and multi-GPU programming**

Processing time with “multithreading” and “multi-GPUs” (mean of 60 views)



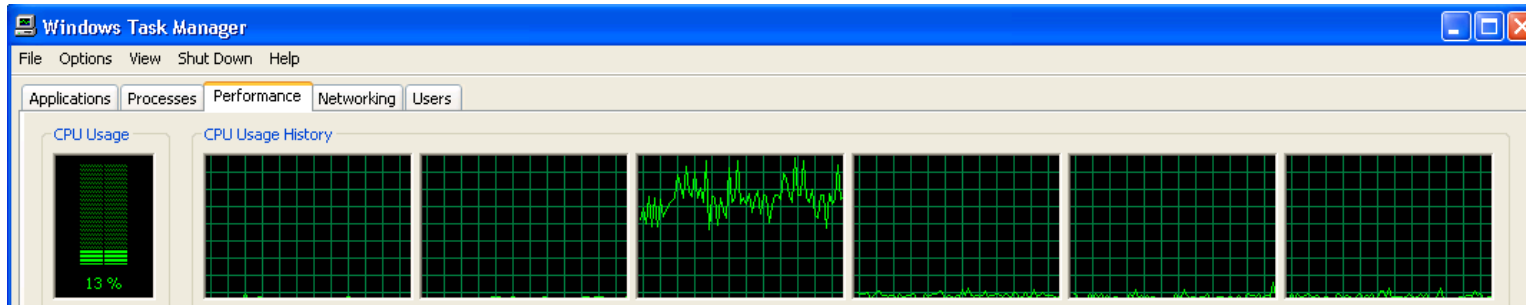
- Multithreading x multi-GPUs allow to reduce tracking time factor 70.
CPU : i7- 3930K 6 cores, 12 threads, 3.2 GHz, GPU : Geforce GTX TITAN, 2688 cuda cores

Summary

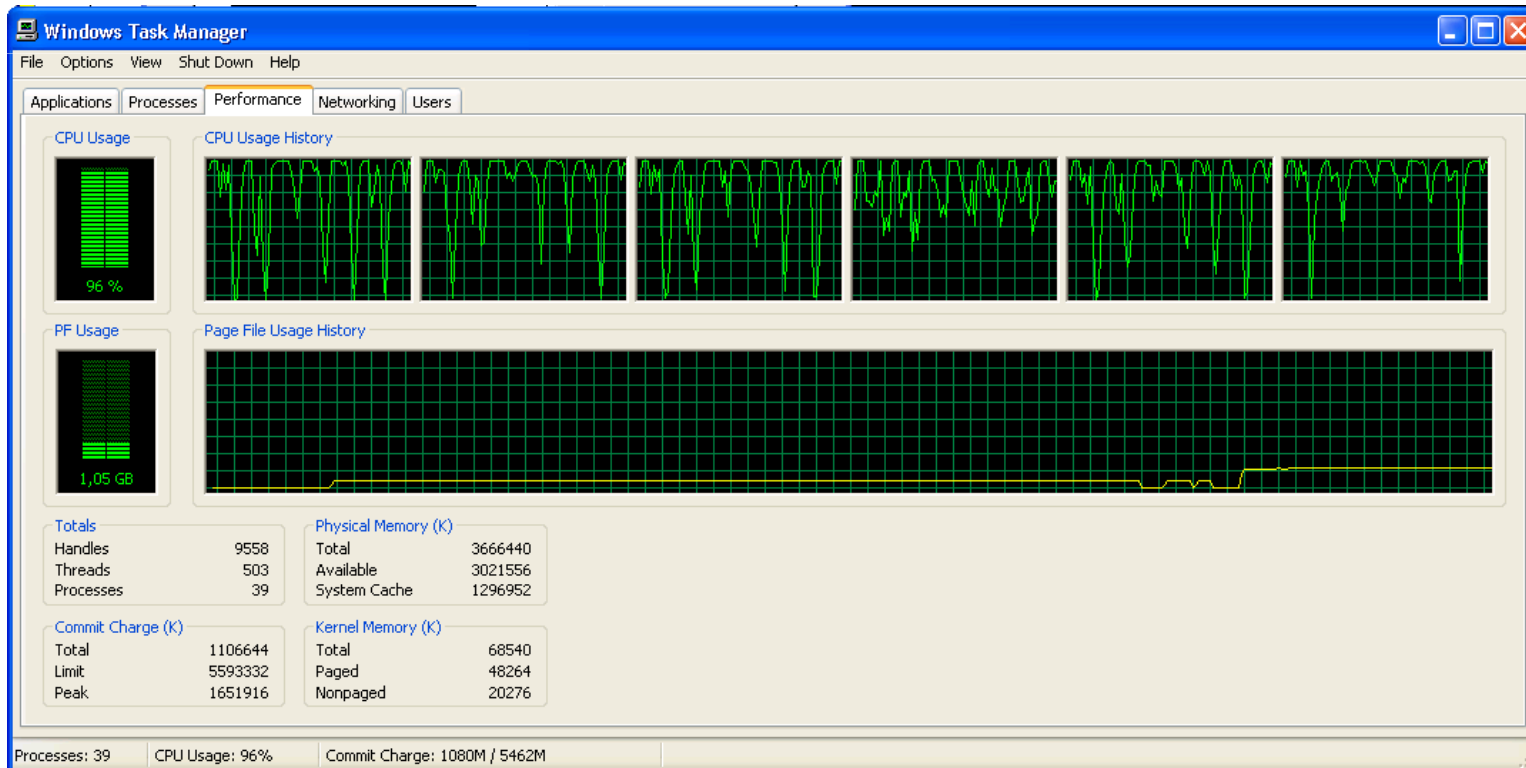
- A new framework for general purpose emulsion scanning/reconstruction is being developed in LHEP Bern
 - From data taking to display
- Fast 4π tracking is realized with GPU with a reasonable processing time
 - 0.14 sec/view, even with a factor 100 more computation than the OPERA algo.
 - $>10\text{cm}^2/\text{h}$
- The system is being applied to AEgIS, neutron projects and the other applications
- Further improvement in processing speed and tracking performance are expected.

Multi-thread processing

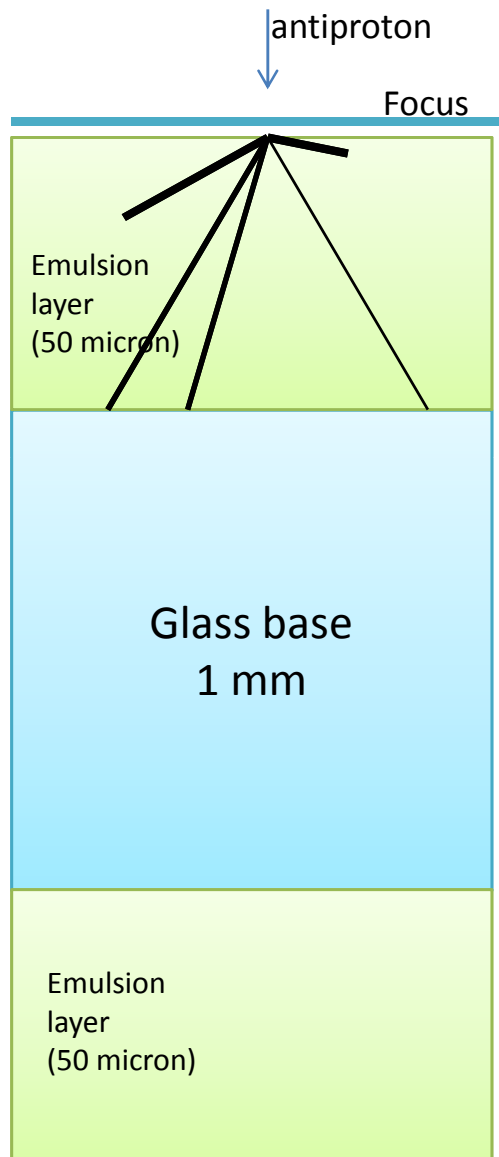
- Single process



- Multi-thread



Antiproton annihilation in the emulsion AEgIS commissioning run (2012)



← 200 microns 23 →